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ARKANSAS DEPARTMENT OF TRANSPORTATION **AUTONOMOUS VEHICLE PILOT PROGRAM RULES**

BUREAU OF LEGISLATIVE RESEARCH

I. Introduction

Pursuant to Arkansas Code Annotated (A.C.A.) § 27-51-2002, the Arkansas State Highway Commission (Commission) may approve a proposed autonomous vehicle pilot program submitted by a person. These rules are issued in accord with the statutory authority set out in subsection (d).

II. Definitions

- (a) As used in these rules:
 - (1) "Automated driving system" means the hardware and software that are collectively capable of performing the entire dynamic driving task on a sustained basis, regardless of whether the automated driving system is limited to a specific Operational Design Domain.
 - (A) An Operational Design Domain (ODD) is the description of the specific operating domain(s) in which an automated function or system is designed to properly operate, including but not limited to roadway types, speed range, environmental conditions (weather, daytime/nighttime, etc.), and other domain constraints.
 - (2) "Autonomous vehicle" means a vehicle equipped with an automated driving system that can drive the vehicle for any duration of time without the active physical control or monitoring of a human operator.
 - (3) "Dynamic driving task" means the real-time operational and tactical functions required to operate a vehicle in on-road traffic, including without limitation the operational functions of:
 - (A) Lateral vehicle motion control via steering;
 - (B) Longitudinal motion control via acceleration and deceleration;
 - (C) Monitoring of the driving environment using object and event detection, recognition, classification, and response preparation;
 - (D) Object and event response execution;
 - (E) Maneuver planning; and
 - (F) Lighting and signaling operation designed to enhance conspicuity of the vehicle.
 - (4) "Dynamic driving task" does not include the strategic functions of:
 - (A) Trip scheduling; or
 - (B) Selection of destinations and waypoints.
 - (5) "Fully autonomous vehicle" means a vehicle equipped with an automated driving system designed to function as a level four-"high automation" or level five-"full automation" system under Society of Automobile Engineers "Taxonomy and Definitions

for Terms Related to Driving Automation Systems for On-Road Motor Vehicles and may be designed to function solely by use of the automated driving system, or when the automated driving system is not engaged, to permit operation by a human operator.

- (6) "Person" means every natural person, firm, co-partnership, association, corporation, or any political subdivision of the State of Arkansas, individually or collectively, including all counties, municipal corporations, public transit authorities, school districts, and special improvement districts.
- (7) "Minimal risk condition" means a low-risk operating mode in which a fully autonomous vehicle operating without a human operator is brought to a complete stop upon experiencing a failure of the vehicle's automated driving system that renders the vehicle unable to perform the entire dynamic driving task.
- (8) "Disengagement of the autonomous mode" means a deactivation of the autonomous mode when a failure of the autonomous technology is detected or when the safe operation of the vehicle requires that a human operator that is physically in the vehicle or that is remotely located takes control of the vehicle.

III. Application

- (a) Any person seeking approval for an autonomous vehicle pilot program shall submit to the Commission an application providing the following information:
 - (1) A statement of the commercial purpose of the autonomous vehicle pilot program;
 - (2) The identification of any additional requirements for proof of insurance under the Motor Vehicle Safety Responsibility Act, A.C.A. §§ 27-19-101 et seq., and 27-22-101 et seq.;
 - (3) A statement acknowledging that:
 - (A) The autonomous vehicle or fully autonomous vehicle is capable of complying with all applicable traffic and motor vehicle safety laws of this state and rules adopted by the Office of Motor Vehicle, including without limitation the laws and rules concerning the capability to safely negotiate railroad crossings unless an exemption for the operation of autonomous vehicles or fully autonomous vehicles at railroad crossings has been obtained from the owner of the railroad by the person submitting the application;
 - (B) The fully autonomous vehicle is capable of achieving a reasonably safe state or "minimal risk condition" if a failure of the automated driving system occurs that renders the automated driving system unable to perform the entire dynamic driving task; and
 - (C) A fully autonomous vehicle involved in a motor vehicle accident is capable of meeting the requirements of A.C.A. §§ 27-53-101, 27-53-102, and 27-53-105.
 - (4) A description of how a fully autonomous vehicle is capable of meeting the requirement of the statement required in A.C.A. § 27-51-2002 (b)(3)(C).

- IV. Application Review, Approval, Denial, or Withdrawal of Approval
 - (a) Upon receipt of an application, the Commission will refer it for consideration to the Director of the Arkansas Department of Transportation.
 - (b) An autonomous vehicle pilot program is automatically approved sixty days after the date of submission of the application to Commission unless the Director approves or denies the application prior to the end of the sixty days.
 - (c) The Director will:
 - (1) Review the application, and approve or deny the application based upon its compliance with these rules; and
 - (2) Notify the applicant of the decision in writing.
 - (d) The Director can withdraw approval of an autonomous vehicle pilot program at any time for any reason. If approval of an autonomous vehicle pilot program is withdrawn, the Director will notify the applicant of the decision in writing.
 - (e) The applicable administrative adjudication provisions of the Arkansas Administrative Procedure Act found in A.C.A. §§ 25-15-208 to -210, and §§ 25-15-212 to -214, shall apply to a decision of the Director to deny or withdraw an application.

V. Operational Allowances and Limitations

- (a) Upon approval of an autonomous vehicle pilot program, a person may operate a maximum of three autonomous vehicles or fully autonomous vehicles simultaneously on the streets and highways of this State;
- (b) During the first six months of an approved autonomous vehicle pilot program, a human operator will be required to be physically present in the vehicle while it is operating on the streets and highways of this State;
- (c) After completion of the first six months of the autonomous vehicle pilot program, an application may be submitted to the Commission to remove the requirement of a human operator to be physically present in the vehicle while it is operating on the streets and highways of this State providing the following information:
 - (1) A copy of the approved application for the autonomous vehicle pilot program;
 - (2) Total number of trips accomplished;
 - (3) Total number of miles traveled;
 - (4) Total number of times a disengagement of the autonomous mode occurred;
 - (5) A copy of all law enforcement accident reports that have involved an autonomous vehicle operating under the autonomous vehicle pilot program or a statement that no accidents have occurred that involved an autonomous vehicle operating under the autonomous vehicle pilot program; and
- (d) The review, approval, denial, or withdrawal of approval of the application to remove the requirement of a human operator to be physically present in the vehicle will be handled as noted in section IV of these rules.

- (e) Upon approval of an autonomous vehicle pilot program that does not require a human operator to be physically present in the vehicle, a person may operate autonomous vehicles or fully autonomous vehicles that are not equipped with the following:
 - (1) Seat belts;
 - (2) A steering wheel; and
 - (3) A rearview mirror.
- (f) If a vehicle operating under an autonomous vehicle pilot program is involved in a serious injury or fatal accident, the following actions will be taken:
 - (1) The person responsible for the autonomous vehicle pilot program will notify the Director immediately;
 - (2) All vehicles operating under the autonomous vehicle pilot program will cease operations until a review of the accident can be completed;
 - (3) The person responsible for the autonomous vehicle pilot program will submit the following to the Director:
 - (A) A copy of the accident report;
 - (B) A report of actions taken by the human operator that was physically located within the vehicle or actions taken by the human operator that was remotely located or a statement that no actions were taken by a human operator;
 - (C) A description of actions taken to prevent subsequent accidents;
 - (D) A request to restart operations of the autonomous vehicle pilot program, if the person responsible for the autonomous vehicle pilot program desires to do so:
 - (4) The review, approval, or denial of the application to restart the autonomous vehicle pilot program will be handled as noted in Section IV of these rules.

VI. Reporting

- (a) A report will be submitted to the Director by January 31st for the previous calendar year's operations providing the following information:
 - (1) A copy of the approved application for the autonomous vehicle pilot program;
 - (2) Total number of trips accomplished;
 - (3) Total number of miles traveled;
 - (4) Total number of times a disengagement of the autonomous mode occurred; and
 - (5) A copy of all law enforcement accident reports that have involved an autonomous vehicle operating under the autonomous vehicle pilot program or a statement that no accidents have occurred that involved an autonomous vehicle operating under the autonomous vehicle pilot program.

Stricken language would be deleted from and underlined language would be added to present law. Act 468 of the Regular Session

1	State of Arkansas	A Bill	
2	92nd General Assembly	A DIII	HOUSE DUL 1561
3	Regular Session, 2019		HOUSE BILL 1561
4			
5	By: Representative McCollum		
6	By: Senator M. Pitsch		
7		E. A. A. T. D. E. Mil. I	
8		For An Act To Be Entitled	
9		THORIZE THE OPERATION OF AUTON	
10		FULLY AUTONOMOUS VEHICLES ON T	
11		OF THIS STATE UNDER AN AUTONO	
12		T PROGRAM; TO DECLARE AN EMERG	ENCY; AND
13	FOR OTHER PU	RPOSES.	
14			
15		C 1441	
16		Subtitle	
17		HORIZE THE OPERATION OF AUTONOM	
18		ES OR FULLY AUTONOMOUS VEHICLES	
19		REETS AND HIGHWAYS OF THIS STAT	ΓE
20		AN AUTONOMOUS VEHICLE PILOT	
21	PROGRAM	1; AND TO DECLARE AN EMERGENCY.	•
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23			
24	BE IT ENACTED BY THE GEN	ERAL ASSEMBLY OF THE STATE OF	ARKANSAS:
25			
26		as Code Title 27, Chapter 51,	-
27		onal section to read as follow	rs:
28		omous vehicle pilot program.	
29	(a) As used in th		
30		ted driving system" means the	·
31	•	pable of performing the entire	
32		gardless of whether the automa	ted driving system is
33		erational design domain;	
34		mous vehicle" means a vehicle	
35		that can drive the vehicle fo	-
36	without the active physi	cal control or monitoring of a	human operator;

1	(3)(A) "Dynamic driving task" means the real-time operational	
2	and tactical functions required to operate a vehicle in on-road traffic,	
3	including without limitation the operational functions of:	
4	(i) Lateral vehicle motion control via steering;	
5	(ii) Longitudinal motion control via acceleration	
6	and deceleration;	
7	(iii) Monitoring of the driving environment using	
8	object and event detection, recognition, classification, and response	
9	preparation;	
10	(iv) Object and event response execution;	
11	(v) Maneuver planning; and	
12	(vi) Lighting and signaling operation designed to	
13	enhance conspicuity of the vehicle.	
14	(B) "Dynamic driving task" does not include the strategic	
15	functions of:	
16	(i) Trip scheduling; or	
17	(ii) Selection of destinations and waypoints;	
18	(4) "Fully autonomous vehicle" means a vehicle equipped with an	
19	automated driving system designed to function as a level four-"high	
20	automation" or level five-"full automation" system under Society of	
21	Automobile Engineers "Taxonomy and Definitions for Terms Related to Driving	
22	<u>Automation Systems for On-Road Motor Vehicles" and may be designed to</u>	
23	function solely by use of the automated driving system, or when the automated	
24	driving system is not engaged, to permit operation by a human operator;	
25	(5) "Minimal risk condition" means a low-risk operating mode in	
26	which a fully autonomous vehicle operating without a human operator is	
27	brought to a complete stop upon experiencing a failure of the vehicle's	
28	automated driving system that renders the vehicle unable to perform the	
29	entire dynamic driving task;	
30	(6) "Operational design domain" means a description of the	
31	specific operating domain in which an automated driving system is designed to	
32	properly operate, including without limitation:	
33	(A) Roadway types;	
34	(B) Speed range:	
35	(C) Environmental conditions; and	
36	(D) Other domain constraints; and	

1	(7) "Person" means every natural person, firm, copartnership,
2	association, corporation, or any political subdivision of the State of
3	Arkansas, individually or collectively, including all counties, municipal
4	corporations, public transit authorities, school districts, and special
5	improvement districts.
6	(b)(1) An autonomous vehicle or a fully autonomous vehicle may be
7	operated in this state under an autonomous vehicle pilot program approved by
8	the State Highway Commission.
9	(2) The autonomous vehicle pilot program is automatically
10	approved sixty (60) days after the date the autonomous vehicle pilot program
11	is submitted to the commission for approval.
12	(c) An autonomous vehicle pilot program shall include without
13	<u>limitation the following:</u>
14	(1) A statement of the commercial purpose of the autonomous
15	vehicle pilot program;
16	(2) The identification of any additional requirements for proof
17	of insurance under the Motor Vehicle Safety Responsibility Act, § 27-19-101
18	et seq., and § 27-22-101 et seq.; and
19	(3) A statement acknowledging that:
20	(A) The autonomous vehicle or fully autonomous vehicle is
21	capable of complying with all applicable traffic and motor vehicle safety
22	laws of this state and rules adopted by the Office of Motor Vehicle;
23	(B) The fully autonomous vehicle is capable of achieving a
24	reasonably safe state if a failure of the automated driving system occurs
25	that renders the automated driving system unable to perform the entire
26	dynamic driving task; and
27	(C) A fully autonomous vehicle involved in a motor vehicle
28	accident is capable of meeting the requirements of §§ 27-53-101, 27-53-102,
29	and 27-53-105; and
30	(4) A description of how a fully autonomous vehicle is capable
31	of meeting the requirement of subdivision (c)(3)(C) of this section.
32	(d) For the purposes of this section, a person may operate:
33	(1) A fully autonomous vehicle that is not equipped with:
34	(A) Seat belts;
35	(B) A steering wheel; or
36	(C) A rearview mirror: and

1	(2) A maximum of three (3) autonomous vehicles or fully
2	autonomous vehicles simultaneously on the streets and highways of this state.
3	(e) The commission shall adopt rules necessary for the implementation
4	of this section.
5	
6	SECTION 2. EMERGENCY CLAUSE. It is found and determined by the
7	General Assembly of the State of Arkansas that to foster innovation and the
8	increased use of technology in Arkansas's transportation system, autonomous
9	vehicle and fully autonomous vehicle testing and operation is necessary.
10	Therefore, an emergency is declared to exist, and this act being immediately
11	necessary for the preservation of the public peace, health, and safety shall
12	become effective on:
13	(1) The date of its approval by the Governor;
14	(2) If the bill is neither approved nor vetoed by the Governor,
15	the expiration of the period of time during which the Governor may veto the
16	<pre>bill; or</pre>
17	(3) If the bill is vetoed by the Governor and the veto is
18	overridden, the date the last house overrides the veto.
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21	APPROVED: 3/14/19
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Stricken language would be deleted from and underlined language would be added to present law. Act 1052 of the Regular Session

1 2	State of Arkansas As Engrossed: $H3/27/19 S4/4/19$ 92nd General Assembly $As Engrossed: Bill$
3	Regular Session, 2019 HOUSE BILL 1822
4	
5	By: Representatives Christiansen, Breaux, Cavenaugh, Dalby, A. Davis, D. Douglas, Eaves, K. Ferguson,
6	Fielding, M. Gray, Hillman, M. Hodges, Rye, Scott, Sorvillo
7	By: Senators J. Dismang, K. Hammer, B. Sample
8	
9	For An Act To Be Entitled
10	AN ACT CONCERNING THE OPERATION OF AUTONOMOUS
11	VEHICLES AT RAILROAD CROSSINGS; TO DECLARE AN
12	EMERGENCY; AND FOR OTHER PURPOSES.
13	
14	
15	Subtitle
16	CONCERNING THE OPERATION OF AUTONOMOUS
17	VEHICLES AT RAILROAD CROSSINGS; AND TO
18	DECLARE AN EMERGENCY.
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21	BE IT ENACTED BY THE GENERAL ASSEMBLY OF THE STATE OF ARKANSAS:
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23	SECTION 1. Arkansas Code § 27-51-1410(c)(3), as amended by Acts 2019
24	No. 468, and concerning an autonomous vehicle pilot program, is amended to
25	read as follows:
26	(3) A statement acknowledging that:
27	(A) (i) The autonomous vehicle or fully autonomous vehicle
28	is capable of complying with all applicable traffic and motor vehicle safety
29	laws of this state and rules adopted by the Office of Motor Vehicle.
30	including without limitation the laws and rules concerning the capability to
31	safely negotiate railroad crossings unless an exemption for the operation of
32	autonomous vehicles or fully autonomous vehicles at railroad crossings is
33	granted by the Arkansas Department of Transportation.
34	(ii) The department shall consult with railroad
35	companies operating in the state when considering an exemption that affects
36	the operation of autonomous vehicles or fully autonomous vehicles at railroad

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1	<pre>crossings;</pre>	
2	(B) The fully autonomous vehicle is capable of achieving a	
3	reasonably safe state if a failure of the automated driving system occurs	
4	that renders the automated driving system unable to perform the entire	
5	dynamic driving task; and	
6	(C) A fully autonomous vehicle involved in a motor vehicle	
7	accident is capable of meeting the requirements of §§ 27-53-101, 27-53-102,	
8	and 27-53-105; and	
9		
10	SECTION 2. EMERGENCY CLAUSE. It is found and determined by the	
11	General Assembly of the State of Arkansas that autonomous vehicles may begin	
12	operating on public streets, roads, and highways as soon as March 14, 2019;	
13	that there may be an issue with negotiating railroad crossings if an	
14	exemption is not granted for autonomous vehicles by the Arkansas Department	
15	of Transportation; and that railroad companies and the department need to be	
16	aware of this issue and work together to resolve this potential issue for the	
17	safety of railroad and motor vehicle traffic. Therefore, an emergency is	
18	declared to exist, and this act being immediately necessary for the	
19	preservation of the public peace, health, and safety shall become effective	
20	<u>on:</u>	
21	(1) The date of its approval by the Governor;	
22	(2) If the bill is neither approved nor vetoed by the Governor,	
23	the expiration of the period of time during which the Governor may veto the	
24	bill; or	
25	(3) If the bill is vetoed by the Governor and the veto is	
26	overridden, the date the last house overrides the veto.	
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29	/s/Christiansen	
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32	APPROVED: 4/16/19	
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